## INTEGRATED CIRCUITS



Product specification Supersedes data of 1998 Jan 06 IC20 Data Handbook

1998 Aug 13





Single-chip 8-bit microcontroller with 10-bit A/D, capture/compare timer, high-speed outputs, PWM

#### **DESCRIPTION** The 80C552/83C552 (hereafter generically referred to as 8XC552) Single-Chip 8-Bit Microcontroller is manufactured in an advanced CMOS process and is a derivative of the 80C51 microcontroller family. The

- of the 80C51 microcontroller family. The 8XC552 has the same instruction set as the 80C51. Three versions of the derivative exist:
- 83C552—8k bytes mask programmable ROM
- 80C552—ROMless version of the 83C552
- 87C552—8k bytes EPROM (described in a separate chapter)

The 8XC552 contains a non-volatile  $8k \times 8$ read-only program memory (83C552), a volatile 256 × 8 read/write data memory, five 8-bit I/O ports, one 8-bit input port, two 16-bit timer/event counters (identical to the timers of the 80C51), an additional 16-bit timer coupled to capture and compare latches, a 15-source, two-priority-level, nested interrupt structure, an 8-input ADC, a dual DAC pulse width modulated interface, two serial interfaces (UART and I<sup>2</sup>C-bus), a "watchdog" timer and on-chip oscillator and timing circuits. For systems that require extra capability, the 8XC552 can be expanded using standard TTL compatible memories and logic.

In addition, the 8XC552 has two software selectable modes of power reduction—idle mode and power-down mode. The idle mode freezes the CPU while allowing the RAM, timers, serial ports, and interrupt system to continue functioning. The power-down mode saves the RAM contents but freezes the oscillator, causing all other chip functions to be inoperative.

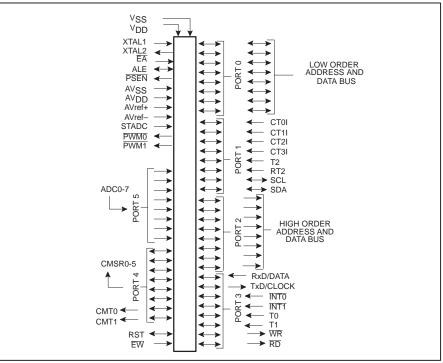
The device also functions as an arithmetic processor having facilities for both binary and BCD arithmetic plus bit-handling capabilities. The instruction set consists of over 100 instructions: 49 one-byte, 45 two-byte, and 17 three-byte. With a 16MHz (24MHz) crystal, 58% of the instructions are executed in 0.75 $\mu$ s (0.5 $\mu$ s) and 40% in 1.5 $\mu$ s (1 $\mu$ s). Multiply and divide instructions require 3 $\mu$ s (2 $\mu$ s).

#### **FEATURES**

- 80C51 central processing unit
- 8k × 8 ROM expandable externally to 64k bytes
- ROM code protection
- An additional 16-bit timer/counter coupled to four capture registers and three compare registers
- Two standard 16-bit timer/counters
- 256 × 8 RAM, expandable externally to 64k bytes
- Capable of producing eight synchronized, timed outputs
- A 10-bit ADC with eight multiplexed analog inputs
- Two 8-bit resolution, pulse width modulation outputs
- Five 8-bit I/O ports plus one 8-bit input port shared with analog inputs

- I<sup>2</sup>C-bus serial I/O port with byte oriented master and slave functions
- Full-duplex UART compatible with the standard 80C51
- On-chip watchdog timer
- Three speed ranges:
  - 3.5 to 16MHz
  - 3.5 to 24MHz (ROM, ROMless only)
  - 3.5 to 30MHz (ROM, ROMless only)
- Three operating ambient temperature ranges:
  - P83C552xBx: 0°C to +70°C
- P83C552xFx: -40°C to +85°C (XTAL frequency max. 24 MHz)
- P83C552xHx: -40°C to +125°C (XTAL frequency max. 16 MHz)

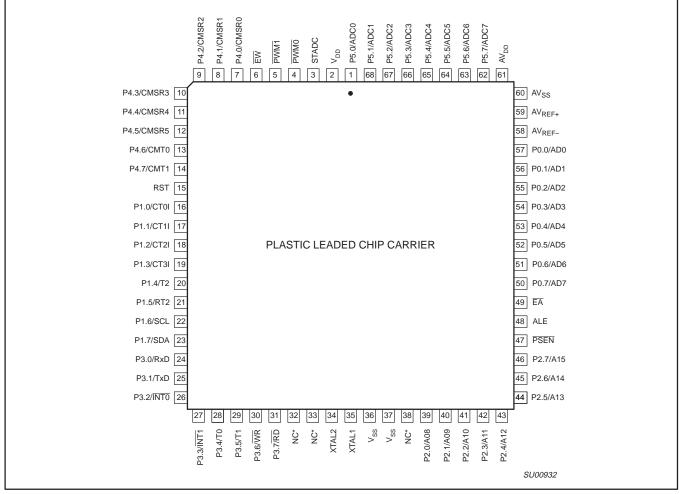
### LOGIC SYMBOL



### 80C552/83C552

### **PIN CONFIGURATIONS**

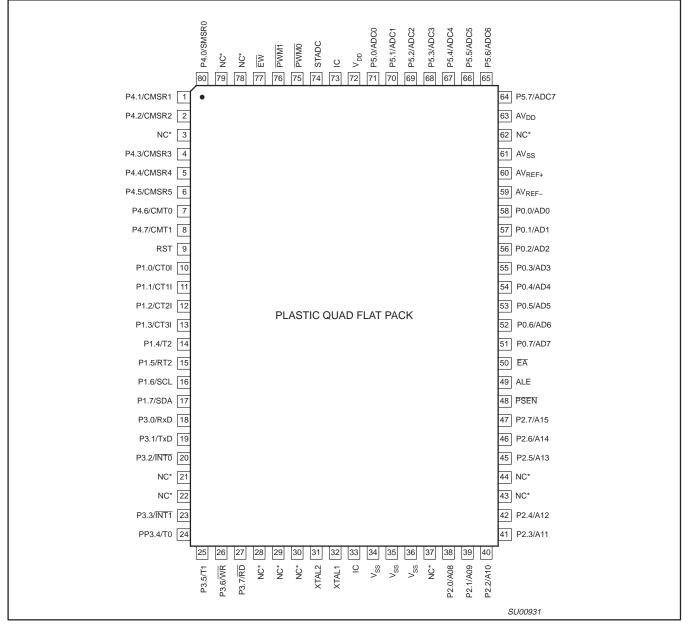
### **Plastic Leaded Chip Carrier**



\* Do not connect.

## 80C552/83C552

### **Plastic Quad Flat Pack**

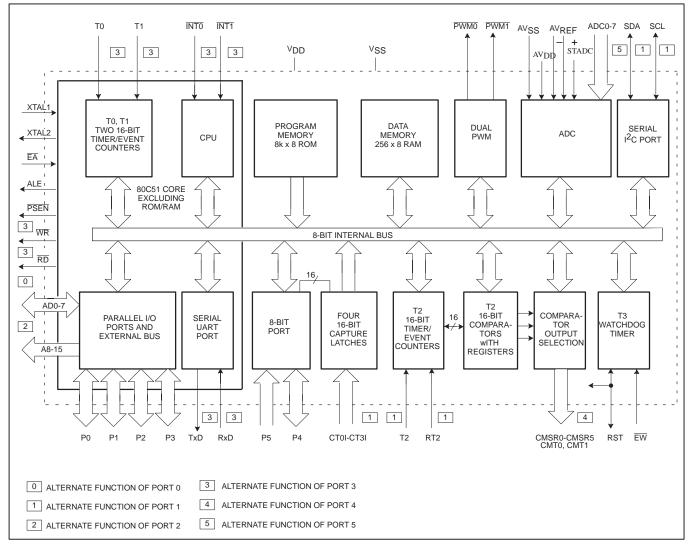


\* Do not connect.

IC = Internally connected (do not use).

### 80C552/83C552

### **BLOCK DIAGRAM**



## 80C552/83C552

#### **ORDERING INFORMATION**

PHILIPS PART ORDER NUMBER PART MARKING		-	TH AMERICA PHI	-	DRAWING NUMBER	TEMPERATURE (°C) AND PACKAGE	FREQ (MHz)
ROMIess	ROM <sup>1</sup>	ROMIess	ROM	EPROM <sup>2</sup>			
P80C552EBA	P83C552EBA/xxx	S80C552-4A68	S83C552-4A68	S87C552-4A68	SOT188-2	0 to +70, Plastic Leaded Chip Carrier	16
P80C552EBB	P83C552EBB/xxx	S80C552-4B	S83C552-4B	S87C552-4BA	SOT318-2	0 to +70, Plastic Quad Flat Pack	16
P80C552EFA	P83C552EFA/xxx	S80C552-5A68	S83C552-5A68	S87C552-5A68	SOT188-2	–40 to +85, Plastic Leaded Chip Carrier	16
P80C552EFB	P83C552EFB/xxx	S80C552-5B	S83C552-5B		SOT318-2	–40 to +85, Plastic Quad Flat Pack	16
P80C552EHA	P83C552EHA/xxx	S80C552-6A68	S83C552-6A68		SOT188-2	–40 to +125, Plastic Leaded Chip Carrier	16
P80C552EHB	P83C552EHB/xxx	S80C552-6B	S83C552-6B		SOT318-2	–40 to +125, Plastic Quad Flat Pack	16
P80C552IBA	P83C552IBA/xxx	S80C552-AA68	S83C552-AA68		SOT188-2	0 to +70, Plastic Leaded Chip Carrier	24
P80C552IBB	P83C552IBB/xxx	S80C552-AB	S83C552-AB		SOT318-2	0 to +70, Plastic Quad Flat Pack	24
P80C552IFA	P83C552IFA/xxx	S80C552-BA68	S83C552-BA68		SOT188-2	–40 to +85, Plastic Leaded Chip Carrier	24
P80C552IFB	P83C552IFB/xxx	S80C552-BB	S83C552-BB		SOT318-2	–40 to +85, Plastic Quad Flat Pack	24
P80C552KBA	P83C552KBA/xxx	S80C552-CA68	S83C552-CA68		SOT188-2	0 to +70, Plastic Leaded Chip Carrier	30
P80C552KBB	P83C552KBB/xxx	S80C552-CB	S83C552-CB		SOT318-2	0 to +70, Plastic Quad Flat Pack	30

NOTE:

xxx denotes the ROM code number.
 For EPROM device specification, refer to *87C552* datasheet.

## 80C552/83C552

### **PIN DESCRIPTION**

	PIN	NO.		
MNEMONIC	PLCC	QFP	TYPE	NAME AND FUNCTION
V <sub>DD</sub>	2	72	I	<b>Digital Power Supply:</b> +5V power supply pin during normal operation, idle and power-down mode.
STADC	3	74	I	<b>Start ADC Operation:</b> Input starting analog to digital conversion (ADC operation can also be started by software). This pin must not float.
PWM0	4	75	0	Pulse Width Modulation: Output 0.
PWM1	5	76	0	Pulse Width Modulation: Output 1.
EW	6	77	I	<b>Enable Watchdog Timer:</b> Enable for T3 watchdog timer and disable power-down mode. This pin must not float.
P0.0-P0.7	57-50	58-51	I/O	<b>Port 0:</b> Port 0 is an 8-bit open-drain bidirectional I/O port. Port 0 pins that have 1s written to them float and can be used as high-impedance inputs. Port 0 is also the multiplexed low-order address and data bus during accesses to external program and data memory. In this application it uses strong internal pull-ups when emitting 1s.
P1.0-P1.7	16-23 16-21 22-23 16-19 20 21 22 23	10-17 10-15 16-17 10-13 14 15 16 17	I/O I/O I I I I I/O I/O	<ul> <li>Port 1: 8-bit I/O port. Alternate functions include:</li> <li>(P1.0-P1.5): Quasi-bidirectional port pins.</li> <li>(P1.6, P1.7): Open drain port pins.</li> <li>CTOI-CT3I (P1.0-P1.3): Capture timer input signals for timer T2.</li> <li>T2 (P1.4): T2 event input.</li> <li>RT2 (P1.5): T2 timer reset signal. Rising edge triggered.</li> <li>SCL (P1.6): Serial port clock line I<sup>2</sup>C-bus.</li> <li>SDA (P1.7): Serial port data line I<sup>2</sup>C-bus.</li> <li>Port 1 is also used to input the lower order address byte during EPROM programming and verification. A0 is on P1.0, etc.</li> </ul>
P2.0-P2.7	39-46	38-42, 45-47	I/O	<b>Port 2:</b> 8-bit quasi-bidirectional I/O port. Alternate function: High-order address byte for external memory (A08-A15).
P3.0-P3.7	24-31	18-20, 23-27	I/O	Port 3: 8-bit quasi-bidirectional I/O port. Alternate functions include:
	24 25 26 27 28 29 30 31	18 19 20 23 24 25 26 27		RxD(P3.0): Serial input port.         TxD (P3.1): Serial output port.         INT0 (P3.2): External interrupt.         INT1 (P3.3): External interrupt.         T0 (P3.4): Timer 0 external input.         T1 (P3.5): Timer 1 external input.         WR (P3.6): External data memory write strobe.         RD (P3.7): External data memory read strobe.
P4.0-P4.7	7-14	80, 1-2 4-8	I/O	Port 4: 8-bit quasi-bidirectional I/O port. Alternate functions include:
	7-12	4-0 80, 1-2 4-6	0	<b>CMSR0-CMSR5 (P4.0-P4.5):</b> Timer T2 compare and set/reset outputs on a match with timer T2.
	13, 14	7, 8	0	CMT0, CMT1 (P4.6, P4.7): Timer T2 compare and toggle outputs on a match with timer T2.
P5.0-P5.7	68-62, 1	71-64,	I	Port 5: 8-bit input port. ADC0-ADC7 (P5.0-P5.7): Alternate function: Eight input channels to ADC.
RST	15	9	I/O	<b>Reset:</b> Input to reset the 8XC552. It also provides a reset pulse as output when timer T3 overflows.
XTAL1	35	32	I	<b>Crystal Input 1:</b> Input to the inverting amplifier that forms the oscillator, and input to the internal clock generator. Receives the external clock signal when an external oscillator is used.
XTAL2	34	31	0	<b>Crystal Input 2:</b> Output of the inverting amplifier that forms the oscillator. Left open-circuit when an external clock is used.

### 80C552/83C552

#### **PIN DESCRIPTION** (Continued)

	PIN	NO.		
MNEMONIC	PLCC	QFP	TYPE	NAME AND FUNCTION
V <sub>SS</sub>	36, 37	34-36	I	Two Digital ground pins.
PSEN	47	48	0	Program Store Enable: Active-low read strobe to external program memory.
ALE	48	49	0	Address Latch Enable: Latches the low byte of the address during accesses to external memory. It is activated every six oscillator periods. During an external data memory access, one ALE pulse is skipped. ALE can drive up to eight LS TTL inputs and handles CMOS inputs without an external pull-up.
ĒĀ	49	50	I	<b>External Access:</b> When $\overline{EA}$ is held at TTL level high, the CPU executes out of the internal program ROM provided the program counter is less than 8192. When $\overline{EA}$ is held at TTL low level, the CPU executes out of external program memory. $\overline{EA}$ is not allowed to float.
AV <sub>REF-</sub>	58	59	I	Analog to Digital Conversion Reference Resistor: Low-end.
AV <sub>REF+</sub>	59	60	I	Analog to Digital Conversion Reference Resistor: High-end.
AV <sub>SS</sub>	60	61	I	Analog Ground
AV <sub>DD</sub>	61	63	I	Analog Power Supply

#### NOTE:

1. To avoid "latch-up" effect at power-on, the voltage on any pin at any time must not be higher or lower than V<sub>DD</sub> + 0.5V or V<sub>SS</sub> – 0.5V, respectively.

#### OSCILLATOR CHARACTERISTICS

XTAL1 and XTAL2 are the input and output, respectively, of an inverting amplifier. The pins can be configured for use as an on-chip oscillator, as shown in the logic symbol, page 2.

To drive the device from an external clock source, XTAL1 should be driven while XTAL2 is left unconnected. There are no requirements on the duty cycle of the external clock signal, because the input to the internal clock circuitry is through a divide-by-two flip-flop. However, minimum and maximum high and low times specified in the data sheet must be observed.

#### RESET

A reset is accomplished by holding the RST pin high for at least two machine cycles (24 oscillator periods), while the oscillator is running. To insure a good power-on reset, the RST pin must be high long enough to allow the oscillator time to start up (normally a few milliseconds) plus two machine cycles. At power-on, the voltage on V<sub>DD</sub> and RST must come up at the same time for a proper start-up.

#### **IDLE MODE**

In the idle mode, the CPU puts itself to sleep while some of the on-chip peripherals stay active. The instruction to invoke the idle mode is the last instruction executed in the normal operating mode before the idle mode is activated. The CPU contents, the on-chip RAM, and all of the special function registers remain intact during this mode. The idle mode can be terminated either by any enabled interrupt (at which time the process is picked up at the interrupt service routine and continued), or by a hardware reset which starts the processor in the same manner as a power-on reset.

#### **POWER-DOWN MODE**

In the power-down mode, the oscillator is stopped and the instruction to invoke power-down is the last instruction executed. Only the contents of the on-chip RAM are preserved. A hardware reset is the only way to terminate the power-down mode. The control bits for the reduced power modes are in the special function register PCON. Table 1 shows the state of the I/O ports during low current operating modes.

# ROM CODE PROTECTION (83C552)

The 83C552 has an additional security feature. ROM code protection may be selected by setting a mask–programmable security bit (i.e., user dependent). This feature may be requested during ROM code submission. When selected, the ROM code is protected and cannot be read out at any time by any test mode or by any instruction in the external program memory space.

The MOVC instructions are the only instructions that have access to program code in the internal or external program memory. The  $\overrightarrow{EA}$  input is latched during RESET and is "don't care" after RESET (also if the security bit is not set). This implementation prevents reading internal program code by switching from external program memory to internal program memory during a MOVC instruction or any other instruction that uses immediate data.

#### Table 1. External Pin Status During Idle and Power-Down Modes

MODE	PROGRAM MEMORY	ALE	PSEN	PORT 0	PORT 1	PORT 2	PORT 3	PORT 4	PWM0/ PWM1
Idle	Internal	1	1	Data	Data	Data	Data	Data	1
Idle	External	1	1	Float	Data	Address	Data	Data	1
Power-down	Internal	0	0	Data	Data	Data	Data	Data	1
Power-down	External	0	0	Float	Data	Data	Data	Data	1

#### Serial Control Register (S1CON) – See Table 2

S1CON (D8H)	CR2	ENS1	STA	STO	SI	AA	CR1	CR0	
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Bits CR0, CR1 and CR2 determine the serial clock frequency that is generated in the master mode of operation.

#### Table 2. Serial Clock Rates

				BIT FRE	QUENCY (kHz)	AT f <sub>OSC</sub>		
CR2	CR1	CR0	6MHz	12MHz	16MHz	24MHz <sup>2</sup>	30MHz <sup>2</sup>	f <sub>OSC</sub> DIVIDED BY
0	0	0	23	47	62.5	94	117 1	256
0	0	1	27	54	71	107 <sup>1</sup>	134 <sup>1</sup>	224
0	1	0	31	63	83.3	125 <sup>1</sup>	156 <sup>1</sup>	192
0	1	1	37	75	100	150 <sup>1</sup>	188 <sup>1</sup>	160
1	0	0	6.25	12.5	17	25	31	960
1	0	1	50	100	133 <sup>1</sup>	200 <sup>1</sup>	250 <sup>1</sup>	120
1	1	0	100	200	267 <sup>1</sup>	400 <sup>1</sup>	500 <sup>1</sup>	60
1	1	1	0.24 < 62.5	0.49 < 62.5	0.65 < 55.6	0.98 < 50.0	1.22 < 52.1	$96 \times (256 - (reload value Timer 1))$
			0 < 255	0 < 254	0 < 253	0 <251	0 < 250	reload value Timer 1 in Mode 2.

NOTES:

1. These frequencies exceed the upper limit of 100kHz of the I<sup>2</sup>C-bus specification and cannot be used in an I<sup>2</sup>C-bus application.

2. At  $f_{OSC} = 24MHz/30MHz$  the maximum I<sup>2</sup>C bus rate of 100kHz cannot be realized due to the fixed divider rates.

### ABSOLUTE MAXIMUM RATINGS<sup>1, 2, 3</sup>

PARAMETER	RATING	UNIT
Storage temperature range	-65 to +150	°C
Voltage on any other pin to $V_{SS}$	-0.5 to +6.5	V
Input, output DC current on any single I/O pin	5.0	mA
Power dissipation (based on package heat transfer limitations, not device power consumption)	1.0	W

NOTES:

 Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any conditions other than those described in the AC and DC Electrical Characteristics section of this specification is not implied.

2. This product includes circuitry specifically designed for the protection of its internal devices from the damaging effects of excessive static charge. Nonetheless, it is suggested that conventional precautions be taken to avoid applying greater than the rated maxima.

3. Parameters are valid over operating temperature range unless otherwise specified. All voltages are with respect to V<sub>SS</sub> unless otherwise noted.

#### **DEVICE SPECIFICATIONS**

	SUPPLY VO	DLTAGE (V)	FREQUEN	ICY (MHz)	
ТҮРЕ	MIN	MAX	MIN	MAX	TEMPERATURE RANGE (°C)
P83(0)C552EBx	4.5	5.5	3.5	16	0 to +70
P83(0)C552EFx	4.5	5.5	3.5	16	-40 to +85
P83(0)C552EHx	4.5	5.5	3.5	16	-40 to +125
P83(0)C552IBx	4.5	5.5	3.5	24	0 to +70
P83(0)C552IFx	4.5	5.5	3.5	24	-40 to +85
P83(0)C552KBx	4.5	5.5	3.5	30	0 to +70

## 80C552/83C552

### DC ELECTRICAL CHARACTERISTICS

		TEST	LIN	IITS	
SYMBOL	PARAMETER	CONDITIONS	MIN	MAX	UNIT
I <sub>DD</sub>	Supply current operating: P83(0)C552EBx P83(0)C552EFx P83(0)C552EHx P83(0)C552IBx P83(0)C552IFx P83(0)C552IFx P83(0)C552KBx	See notes 1 and 2 $f_{OSC} = 16MHz$ $f_{OSC} = 16MHz$ $f_{OSC} = 16MHz$ $f_{OSC} = 24MHz$ $f_{OSC} = 24MHz$ $f_{OSC} = 30MHz$		45 45 40 55 55 68	mA mA mA mA mA
I <sub>ID</sub>	Idle mode: P83(0)C552EBx P83(0)C552EFx P83(0)C552EHx P83(0)C552IBx P83(0)C552IFx P83(0)C552IFx P83(0)C552KBx	See notes 1 and 3 $f_{OSC} = 16MHz$ $f_{OSC} = 16MHz$ $f_{OSC} = 16MHz$ $f_{OSC} = 24MHz$ $f_{OSC} = 24MHz$ $f_{OSC} = 30MHz$		10 10 9 12.5 12.5 15	mA mA mA mA mA
I <sub>PD</sub>	Power-down current: P83(0)C552xBx P83(0)C552xFx P83(0)C552xHx	See notes 1 and 4; 2V < V <sub>PD</sub> < V <sub>DD</sub> max		50 50 150	μΑ μΑ μΑ
Inputs	-				
V <sub>IL</sub>	Input low voltage, except EA, P1.6, P1.7		-0.5	0.2V <sub>DD</sub> -0.1	V
V <sub>IL1</sub>	Input low voltage to EA		-0.5	0.2V <sub>DD</sub> -0.3	V
V <sub>IL2</sub>	Input low voltage to P1.6/SCL, P1.7/SDA <sup>5</sup>		-0.5	0.3V <sub>DD</sub>	V
$V_{\text{IH}}$	Input high voltage, except XTAL1, RST, P1.6/SCL, P1.7/SDA		0.2V <sub>DD</sub> +0.9	V <sub>DD</sub> +0.5	V
V <sub>IH1</sub>	Input high voltage, XTAL1, RST		0.7V <sub>DD</sub>	V <sub>DD</sub> +0.5	V
V <sub>IH2</sub>	Input high voltage, P1.6/SCL, P1.7/SDA <sup>5</sup>		0.7V <sub>DD</sub>	6.0	V
IIL	Logical 0 input current, ports 1, 2, 3, 4, except P1.6, P1.7	V <sub>IN</sub> = 0.45V		-50	μΑ
I <sub>TL</sub>	Logical 1-to-0 transition current, ports 1, 2, 3, 4, except P1.6, P1.7	See note 6		-650	μA
$\pm I_{\text{IL1}}$	Input leakage current, port 0, EA, STADC, EW	0.45V < V <sub>I</sub> < V <sub>DD</sub>		10	μA
$\pm I_{\text{IL2}}$	Input leakage current, P1.6/SCL, P1.7/SDA	0V < V <sub>I</sub> < 6V 0V < V <sub>DD</sub> < 5.5V		10	μΑ
$\pm I_{\text{IL3}}$	Input leakage current, port 5	$0.45V < V_{1} < V_{DD}$		1	μA
Outputs					
V <sub>OL</sub>	Output low voltage, ports 1, 2, 3, 4, except P1.6, P1.7	$I_{OL} = 1.6 m A^7$		0.45	V
V <sub>OL1</sub>	Output low voltage, port 0, ALE, PSEN, PWM0, PWM1	$I_{OL} = 3.2 m A^7$		0.45	V
V <sub>OL2</sub>	Output low voltage, P1.6/SCL, P1.7/SDA	$I_{OL} = 3.0 \text{mA}^7$		0.4	V
V <sub>OH</sub>	Output high voltage, ports 1, 2, 3, 4, except P1.6/SCL, P1.7/SDA	-I <sub>OH</sub> = 60μA -I <sub>OH</sub> = 25μA -I <sub>OH</sub> = 10μA	2.4 0.75V <sub>DD</sub> 0.9V <sub>DD</sub>		V V V
V <sub>OH1</sub>	Output high voltage (port 0 in external bus mode, ALE, PSEN, PWM0, PWM1) <sup>8</sup>	-I <sub>OH</sub> = 400μA -I <sub>OH</sub> = 150μA -I <sub>OH</sub> = 40μA	2.4 0.75V <sub>DD</sub> 0.9V <sub>DD</sub>		V V V
V <sub>OH2</sub>	Output high voltage (RST)	–l <sub>OH</sub> = 400μA –l <sub>OH</sub> = 120μA	2.4 0.8V <sub>DD</sub>		V V
R <sub>RST</sub>	Internal reset pull-down resistor		50	150	kΩ
C <sub>IO</sub>	Pin capacitance	Test freq = 1MHz, T <sub>amb</sub> = 25°C		10	pF

### 80C552/83C552

### DC ELECTRICAL CHARACTERISTICS (Continued)

		TEST	LIN	IITS	
SYMBOL	PARAMETER	CONDITIONS	MIN	MAX	UNIT
Analog In	puts	·			
AI <sub>DD</sub>	Analog supply current: operating: (16MHz) Analog supply current: operating: (24MHz, 30MHz)	Port 5 = 0 to $AV_{DD}$ Port 5 = 0 to $AV_{DD}$		1.2 1.0	mA mA
AI <sub>ID</sub>	Idle mode: P83(0)C552EBx P83(0)C552EFx P83(0)C552EHx P83(0)C552IBx P83(0)C552IFx P83(0)C552IFx P83(0)C552KBx			50 50 100 50 50 50	μΑ μΑ μΑ μΑ μΑ μΑ
Al <sub>PD</sub>	Power-down mode: P83(0)C552xBx P83(0)C552xFx P83(0)C552xFx P83(0)C552xHx	2V < AV <sub>PD</sub> < AV <sub>DD</sub> max		50 50 100	μΑ μΑ μΑ
AV <sub>IN</sub>	Analog input voltage		AV <sub>SS</sub> -0.2	AV <sub>DD</sub> +0.2	V
AV <sub>REF</sub>	Reference voltage: AV <sub>REF-</sub> AV <sub>REF+</sub>		AV <sub>SS</sub> -0.2	AV <sub>DD</sub> +0.2	V V
R <sub>REF</sub>	Resistance between AV <sub>REF+</sub> and AV <sub>REF-</sub>		10	50	kΩ
CIA	Analog input capacitance			15	pF
t <sub>ADS</sub>	Sampling time			8t <sub>CY</sub>	μs
t <sub>ADC</sub>	Conversion time (including sampling time)			50t <sub>CY</sub>	μs
DLe	Differential non-linearity <sup>10, 11, 12</sup>			±1	LSB
ILe	Integral non-linearity <sup>10, 13</sup>			±2	LSB
OS <sub>e</sub>	Offset error <sup>10, 14</sup>			±2	LSB
G <sub>e</sub>	Gain error <sup>10, 15</sup>			±0.4	%
A <sub>e</sub>	Absolute voltage error <sup>10, 16</sup>			±3	LSB
M <sub>CTC</sub>	Channel to channel matching			±1	LSB
Ct	Crosstalk between inputs of port 5 <sup>17</sup>	0–100kHz		-60	dB

NOTES FOR DC ELECTRICAL CHARACTERISTICS:

1. See Figures 10 through 15 for I<sub>DD</sub> test conditions.

The operating supply current is measured with all output pins disconnected; XTAL1 driven with  $t_r = t_f = 10ns$ ;  $V_{IL} = V_{SS} + 0.5V$ ; 2.  $V_{IH} = V_{DD} - 0.5V$ ; XTAL2 not connected;  $\overline{EA} = RST = Port 0 = \overline{EW} = V_{DD}$ ; STADC =  $V_{SS}$ .

The idle mode supply current is measured with all output pins disconnected; XTAL1 driven with  $t_r = t_f = 10ns$ ;  $V_{IL} = V_{SS} + 0.5V$ ; 3.  $V_{IH} = V_{DD} - 0.5V$ ; XTAL2 not connected; Port  $0 = \overline{EW} = V_{DD}$ ;  $\overline{EA} = RST = STADC = V_{SS}$ .

The power-down current is measured with all output pins disconnected; XTAL2 not connected; Port 0 =  $\overline{EW} = V_{DD}$ ; 4.  $\overline{EA}$  = RST = STADC = XTAL1 = V<sub>SS</sub>.

The input threshold voltage of P1.6 and P1.7 (SIO1) meets the I<sup>2</sup>C specification, so an input voltage below 1.5V will be recognized as a logic 0 while an input voltage above 3.0V will be recognized as a logic 1.

6. Pins of ports 1 (except P1.6, P1.7), 2, 3, and 4 source a transition current when they are being externally driven from 1 to 0. The transition current reaches its maximum value when VIN is approximately 2V.

7. Capacitive loading on ports 0 and 2 may cause spurious noise to be superimposed on the Vols of ALE and ports 1 and 3. The noise is due to external bus capacitance discharging into the port 0 and port 2 pins when these pins make 1-to-0 transitions during bus operations. In the worst cases (capacitive loading > 100pF), the noise pulse on the ALE pin may exceed 0.8V. In such cases, it may be desirable to qualify ALE with a Schmitt Trigger, or use an address latch with a Schmitt Trigger STROBE input. IoL can exceed these conditions provided that no single output sinks more than 5mA and no more than two outputs exceed the test conditions.

Capacitive loading on ports 0 and 2 may cause the VOH on ALE and PSEN to momentarily fall below the 0.9VDD specification when the 8. address bits are stabilizing.

9. The following condition must not be exceeded: V<sub>DD</sub> - 0.2V < AV<sub>DD</sub> < V<sub>DD</sub> + 0.2V.
10. Conditions: AV<sub>REF</sub> = 0V; AV<sub>DD</sub> = 5.0V, AV<sub>REF+</sub> (80C552, 83C552) = 5.12V. ADC is monotonic with no missing codes. Measurement by continuous conversion of AV<sub>IN</sub> = -20mV to 5.12V in steps of 0.5mV.
11. The differential non-linearity (DL<sub>e</sub>) is the difference between the actual step width and the ideal step width. (See Figure 1.)

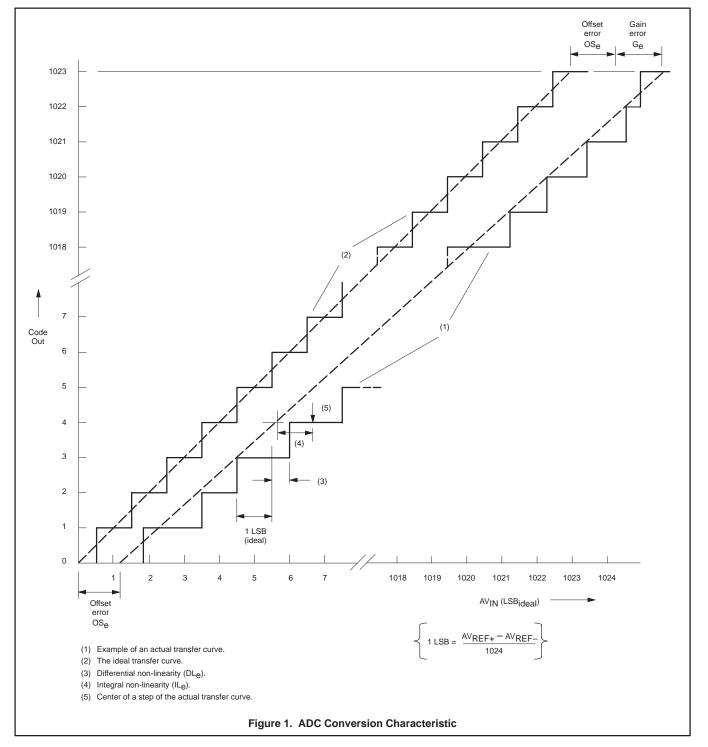
12. The ADC is monotonic; there are no missing codes.

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## Single-chip 8-bit microcontroller

- 13. The integral non-linearity (IL<sub>e</sub>) is the peak difference between the center of the steps of the actual and the ideal transfer curve after appropriate adjustment of gain and offset error. (See Figure 1.)
- 14. The offset error (OS<sub>e</sub>) is the absolute difference between the straight line which fits the actual transfer curve (after removing gain error), and a straight line which fits the ideal transfer curve. (See Figure 1.)
- 15. The gain error (G<sub>e</sub>) is the relative difference in percent between the straight line fitting the actual transfer curve (after removing offset error), and the straight line which fits the ideal transfer curve. Gain error is constant at every point on the transfer curve. (See Figure 1.)
- 16. The absolute voltage error (A<sub>e</sub>) is the maximum difference between the center of the steps of the actual transfer curve of the non-calibrated ADC and the ideal transfer curve.

17. This should be considered when both analog and digital signals are simultaneously input to port 5.



## 80C552/83C552

### AC ELECTRICAL CHARACTERISTICS<sup>1, 2</sup>

16 MHz version

			16MHz	CLOCK	VARIABL	E CLOCK	
SYMBOL	FIGURE	PARAMETER	MIN	MAX	MIN	MAX	υνιτ
1/t <sub>CLCL</sub>	2	Oscillator frequency			3.5	16	MHz
LHLL	2	ALE pulse width	85		2t <sub>CLCL</sub> -40		ns
AVLL	2	Address valid to ALE low	8		t <sub>CLCL</sub> -55		ns
LLAX	2	Address hold after ALE low	28		t <sub>CLCL</sub> -35		ns
t <sub>LLIV</sub>	2	ALE low to valid instruction in		150		4t <sub>CLCL</sub> -100	ns
t <sub>LLPL</sub>	2	ALE low to PSEN low	23		t <sub>CLCL</sub> -40		ns
t <sub>PLPH</sub>	2	PSEN pulse width	143		3t <sub>CLCL</sub> -45		ns
t <sub>PLIV</sub>	2	PSEN low to valid instruction in		83		3t <sub>CLCL</sub> -105	ns
t <sub>PXIX</sub>	2	Input instruction hold after PSEN	0		0		ns
t <sub>PXIZ</sub>	2	Input instruction float after PSEN		38		t <sub>CLCL</sub> -25	ns
t <sub>AVIV</sub>	2	Address to valid instruction in		208		5t <sub>CLCL</sub> -105	ns
t <sub>PLAZ</sub>	2	PSEN low to address float		10		10	ns
Data Memo	ory			•			
t <sub>RLRH</sub>	3	RD pulse width	275		6t <sub>CLCL</sub> -100		ns
twlwh	4	WR pulse width	275		6t <sub>CLCL</sub> -100	İ	ns
t <sub>RLDV</sub>	3	RD low to valid data in		148		5t <sub>CLCL</sub> -165	ns
t <sub>RHDX</sub>	3	Data hold after RD	0		0		ns
t <sub>RHDZ</sub>	3	Data float after RD		55		2t <sub>CLCL</sub> -70	ns
t <sub>LLDV</sub>	3	ALE low to valid data in		350		8t <sub>CLCL</sub> -150	ns
t <sub>AVDV</sub>	3	Address to valid data in		398		9t <sub>CLCL</sub> -165	ns
t <sub>LLWL</sub>	3, 4	ALE low to RD or WR low	138	238	3t <sub>CLCL</sub> -50	3t <sub>CLCL</sub> +50	ns
t <sub>AVWL</sub>	3, 4	Address valid to WR low or RD low	120		4t <sub>CLCL</sub> -130		ns
t <sub>QVWX</sub>	4	Data valid to WR transition	3		t <sub>CLCL</sub> -60		ns
t <sub>DW</sub>	4	Data before WR	288		7t <sub>CLCL</sub> -150		ns
t <sub>WHQX</sub>	4	Data hold after WR	13		t <sub>CLCL</sub> -50		ns
t <sub>RLAZ</sub>	3	RD low to address float		0		0	ns
t <sub>WHLH</sub>	3, 4	RD or WR high to ALE high	23	103	t <sub>CLCL</sub> -40	t <sub>CLCL</sub> +40	ns
External Cl	ock		I		0101	0101	
t <sub>CHCX</sub>	5	High time <sup>4</sup>	20		20		ns
t <sub>CLCX</sub>	5	Low time <sup>4</sup>	20		20		ns
<sup>t</sup> CLCH	5	Rise time <sup>4</sup>		20		20	ns
CHCL	5	Fall time <sup>4</sup>		20		20	ns
	ng – Shift R	egister Mode <sup>4</sup> (Test Conditions: T <sub>amb</sub> = 0	)°C to +70°C; V <sub>SS</sub>	= 0V; Load Capa	citance = 80pF)		
t <sub>XLXL</sub>	6	Serial port clock cycle time	0.75		12t <sub>CLCL</sub>		μs
t <sub>QVXH</sub>	6	Output data setup to clock rising edge	492	1	10t <sub>CLCL</sub> -133		ns
t <sub>XHQX</sub>	6	Output data hold after clock rising edge	8		2t <sub>CLCL</sub> -117		ns
t <sub>XHDX</sub>	6	Input data hold after clock rising edge	0	1	0		ns
	6	Clock rising edge to input data valid	-	492	-	10t <sub>CLCL</sub> -133	ns
ALLAN	· ·		1		1	ULUL 100	

NOTES:

Parameters are valid over operating temperature range unless otherwise specified.
 Load capacitance for port 0, ALE, and PSEN = 100pF, load capacitance for all other outputs = 80pF.
 t<sub>CLCL</sub> = 1/f<sub>OSC</sub> = one oscillator clock period. t<sub>CLCL</sub> = 83.3ns at f<sub>OSC</sub> = 12MHz. t<sub>CLCL</sub> = 62.5ns at f<sub>OSC</sub> = 16MHz.
 These values are characterized but not 100% production tested.

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### AC ELECTRICAL CHARACTERISTICS (Continued)<sup>1, 2</sup>

24/30 MHz version

			24MHz	CLOCK	30MHz	CLOCK	VARIABL		
SYMBOL	FIGURE	PARAMETER	MIN	MAX	MIN	MAX	MIN	MAX	UNIT
1/t <sub>CLCL</sub>	2	Oscillator frequency					3.5	24	MHz
LHLL	2	ALE pulse width	43		27		2t <sub>CLCL</sub> -40		ns
AVLL	2	Address valid to ALE low	17		8		t <sub>CLCL</sub> -25		ns
LLAX	2	Address hold after ALE low	17		8		t <sub>CLCL</sub> –25		ns
t <sub>LLIV</sub>	2	ALE low to valid instruction in		102		68		4t <sub>CLCL</sub> -65	ns
LLPL	2	ALE low to PSEN low	17		8		t <sub>CLCL</sub> –25		ns
t <sub>PLPH</sub>	2	PSEN pulse width	80		55		3t <sub>CLCL</sub> -45		ns
t <sub>PLIV</sub>	2	PSEN low to valid instruction in		65		40		3t <sub>CLCL</sub> –60	ns
<sup>t</sup> PXIX	2	Input instruction hold after PSEN	0		0		0		ns
<sup>t</sup> PXIZ	2	Input instruction float after PSEN		17		8		t <sub>CLCL</sub> -25	ns
t <sub>AVIV</sub>	2	Address to valid instruction in		128		87		5t <sub>CLCL</sub> -80	ns
t <sub>PLAZ</sub>	2	PSEN low to address float		10		10		10	ns
Data Memo	ory	•		•		•			
t <sub>RLRH</sub>	3	RD pulse width	150		100		6t <sub>CLCL</sub> -100		ns
t <sub>WLWH</sub>	4	WR pulse width	150		100		6t <sub>CLCL</sub> -100		ns
RLDV	3	RD low to valid data in		118		77	5t <sub>CLCL</sub> -90		ns
RHDX	3	Data hold after RD	0		0		0		ns
RHDZ	3	Data float after RD		55		39		2t <sub>CLCL</sub> -28	ns
LLDV	3	ALE low to valid data in		183		117		8t <sub>CLCL</sub> -150	ns
t <sub>AVDV</sub>	3	Address to valid data in		210		135		9t <sub>CLCL</sub> -165	ns
LLWL	3, 4	ALE low to RD or WR low	75	175	50	150	3t <sub>CLCL</sub> -50	3t <sub>CLCL</sub> +50	ns
t <sub>avwl</sub>	3, 4	Address valid to WR low or RD low	92		58		4t <sub>CLCL</sub> -75		ns
<sup>t</sup> qvwx	4	Data valid to WR transition	12		3		t <sub>CLCL</sub> -30		ns
t <sub>DW</sub>	4	Data before WR	162		103		7t <sub>CLCL</sub> -130		ns
<sup>t</sup> WHQX	4	Data hold after WR	17		8		t <sub>CLCL</sub> -25		ns
t <sub>RLAZ</sub>	3	RD low to address float		0		0		0	ns
t <sub>WHLH</sub>	3, 4	RD or WR high to ALE high	17	67	8	58	t <sub>CLCL</sub> -25	t <sub>CLCL</sub> +25	ns
External C	lock	•		•	•	•			,
t <sub>СНСХ</sub>	5	High time <sup>3</sup>	17		15		17		ns
t <sub>CLCX</sub>	5	Low time <sup>3</sup>	17		15		17		ns
<sup>t</sup> CLCH	5	Rise time <sup>3</sup>		5		3		20	ns
CHCL	5	Fall time <sup>3</sup>		5		3		20	ns
	ng – Shift R	<b>Register Mode</b> <sup>3</sup> (Test Conditions: $T_{amb} = 0$	)°C to +7	0°C; V <sub>SS</sub>	= 0V; Loa	ad Capac	tance = 80pF)	I	
<sup>t</sup> xlxl	6	Serial port clock cycle time	0.5		0.4		12t <sub>CLCL</sub>		μs
<sup>I</sup> QVXH	6	Output data setup to clock rising edge	283	i	200		10t <sub>CLCL</sub> -133		ns
<sup>t</sup> XHQX	6	Output data hold after clock rising edge	23	i	6.6	İ – – – – – – – – – – – – – – – – – – –	2t <sub>CLCL</sub> -60		ns
	6	Input data hold after clock rising edge	0	1	0		0		ns
	1			1					

 NOTES:
 1. Parameters are valid over operating temperature range unless otherwise specified.

 2. Load capacitance for port 0, ALE, and PSEN = 100pF, load capacitance for all other outputs = 80pF.

 3. These values are characterized but not 100% production tested.

 4. t<sub>CLCL</sub> = 1/f<sub>OSC</sub> = one oscillator clock period. t<sub>CLCL</sub> = 41.7ns at f<sub>OSC</sub> = 24MHz.

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### AC ELECTRICAL CHARACTERISTICS (Continued)

SYMBOL	PARAMETER	INPUT	OUTPUT		
I <sup>2</sup> C Interfa	ce (Refer to Figure 9)		1		
t <sub>HD;STA</sub>	START condition hold time	$\ge$ 14 t <sub>CLCL</sub>	> 4.0µs <sup>1</sup>		
t <sub>LOW</sub>	SCL low time	≥ 16 t <sub>CLCL</sub>	> 4.7µs <sup>1</sup>		
t <sub>HIGH</sub>	SCL high time	$\ge$ 14 t <sub>CLCL</sub>	> 4.0µs <sup>1</sup>		
t <sub>RC</sub>	SCL rise time	≤ 1μs	_ 2		
t <sub>FC</sub>	SCL fall time	≤ 0.3µs	< 0.3µs <sup>3</sup>		
t <sub>SU;DAT1</sub>	Data set-up time	≥ 250ns	> 20 t <sub>CLCL</sub> - t <sub>RD</sub>		
t <sub>SU;DAT2</sub>	SDA set-up time (before rep. START cond.)	≥ 250ns	> 1µs <sup>1</sup>		
t <sub>SU;DAT3</sub>	SDA set-up time (before STOP cond.)	≥ 250ns	> 8 t <sub>CLCL</sub>		
t <sub>HD;DAT</sub>	Data hold time	≥ 0ns	> 8 t <sub>CLCL</sub> - t <sub>FC</sub>		
t <sub>SU;STA</sub>	Repeated START set-up time	≥ 14 t <sub>CLCL</sub>	> 4.7µs <sup>1</sup>		
tsu;sto	STOP condition set-up time	≥ 14 t <sub>CLCL</sub>	> 4.0µs <sup>1</sup>		
t <sub>BUF</sub>	Bus free time	$\ge$ 14 t <sub>CLCL</sub>	> 4.7µs <sup>1</sup>		
t <sub>RD</sub>	SDA rise time	≤ 1μs	_ 2		
t <sub>FD</sub>	SDA fall time	≤ 0.3μs	< 0.3µs <sup>3</sup>		

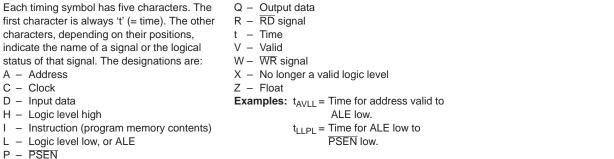
NOTES:

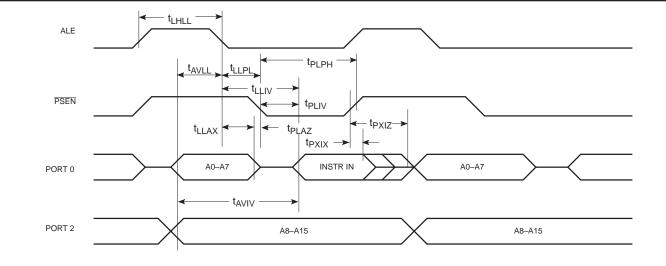
1. At 100 kbit/s. At other bit rates this value is inversely proportional to the bit-rate of 100 kbit/s. 2. Determined by the external bus-line capacitance and the external bus-line pull-resistor, this must be <  $1\mu$ s. 3. Spikes on the SDA and SCL lines with a duration of less than 3 t<sub>CLCL</sub> will be filtered out. Maximum capacitance on bus-lines SDA and SCL = 400pF.

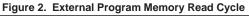
4.  $t_{CLCL} = 1/f_{OSC}$  = one oscillator clock period at pin XTAL1. For 62ns, 42ns, 33.3ns <  $t_{CLCL}$  < 285ns (16MHz, 24MHz, 30MHz >  $f_{OSC}$  > 1.2MHz) the SI01 interface meets the I<sup>2</sup>C-bus specification for bit-rates up to 100 kbit/s.

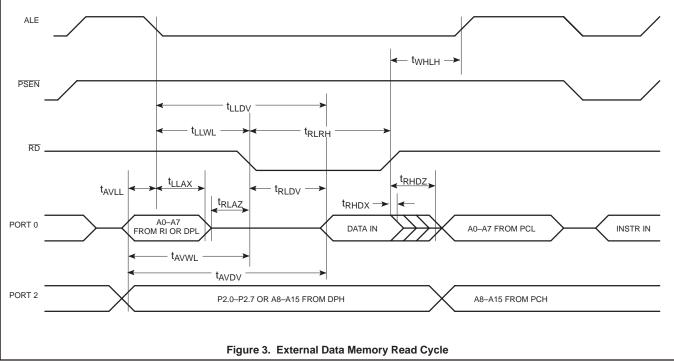
1998 Aug 13

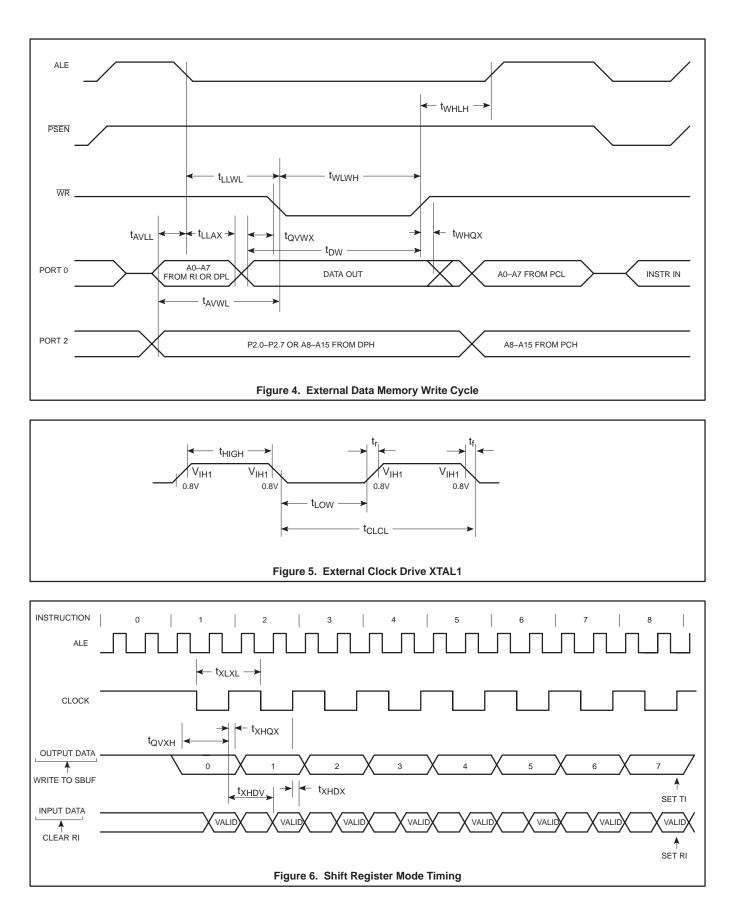
### EXPLANATION OF THE AC SYMBOLS

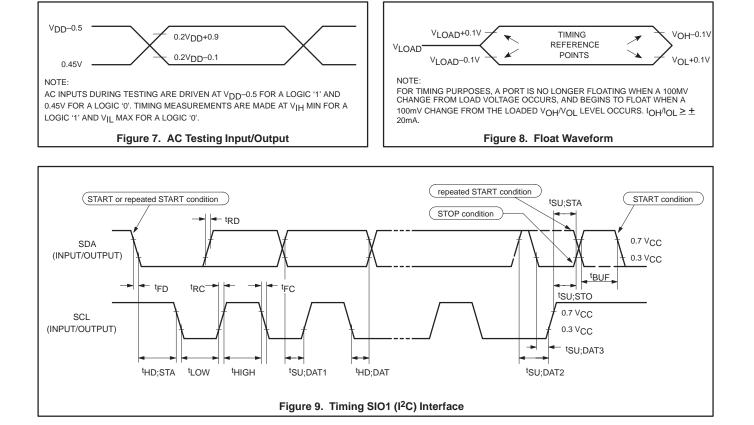


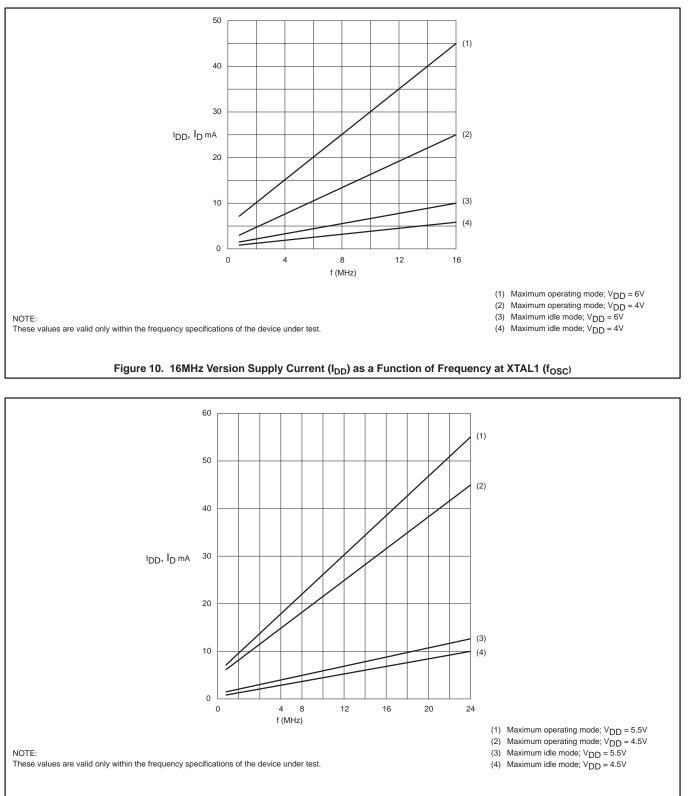


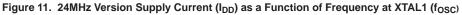




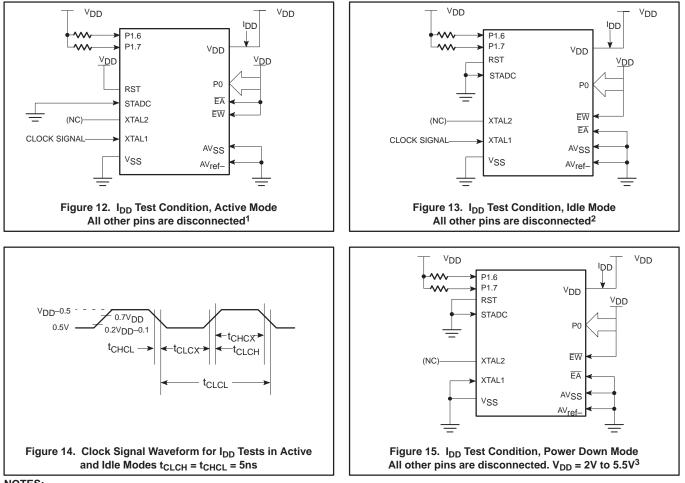








## 80C552/83C552



NOTES:

- 1. Active Mode:
  - a. The following pins must be forced to  $V_{DD}$ :  $\overline{EA}$ , RST, Port 0, and  $\overline{EW}$ .
  - b. The following pins must be forced to V<sub>SS</sub>: STADC, AV<sub>ss</sub>, and AV<sub>ref-</sub>.
  - c. Ports 1.6 and 1.7 should be connected to V<sub>DD</sub> through resistors of sufficiently high value such that the sink current into these pins cannot exceed the I<sub>OL1</sub> spec of these pins.
  - d. The following pins must be disconnected: XTAL2 and all pins not specified above.
- 2. Idle Mode:
  - a. The following pins must be forced to  $V_{\mbox{\scriptsize DD}}\!\!\!\!\!\!$  Port 0 and  $\overline{\mbox{\scriptsize EW}}\!\!\!\!\!$
  - b. The following pins must be forced to V\_SS: RST, STADC, AV\_ss,, AV\_ref-, and  $\overline{\text{EA}}.$
  - c. Ports 1.6 and 1.7 should be connected to V<sub>DD</sub> through resistors of sufficiently high value such that the sink current into these pins cannot exceed the I<sub>OL1</sub> spec of these pins. These pins must not have logic 0 written to them prior to this measurement.
  - d. The following pins must be disconnected: XTAL2 and all pins not specified above.
- 3. Power Down Mode:
  - a. The following pins must be forced to  $V_{\text{DD}}$ : Port 0 and  $\overline{\text{EW}}.$
  - b. The following pins must be forced to V<sub>SS</sub>: RST, STADC, XTAL1, AV<sub>ss</sub>,, AV<sub>ref-</sub>, and  $\overline{EA}$ .
  - c. Ports 1.6 and 1.7 should be connected to  $V_{DD}$  through resistors of sufficiently high value such that the sink current into these pins cannot exceed the  $I_{OL1}$  spec of these pins. These pins must not have logic 0 written to them prior to this measurement.
  - d. The following pins must be disconnected: XTAL2 and all pins not specified above.

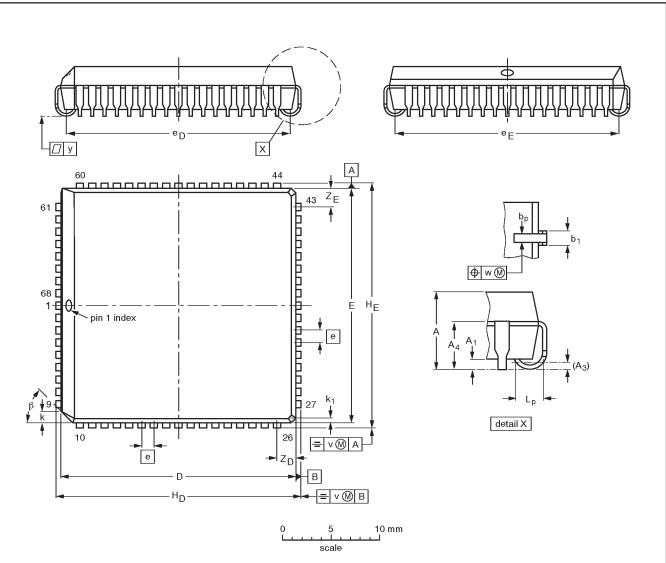


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### 80C552/83C552

### PLCC68: plastic leaded chip carrier; 68 leads

Single-chip 8-bit microcontroller



#### DIMENSIONS (millimetre dimensions are derived from the original inch dimensions)

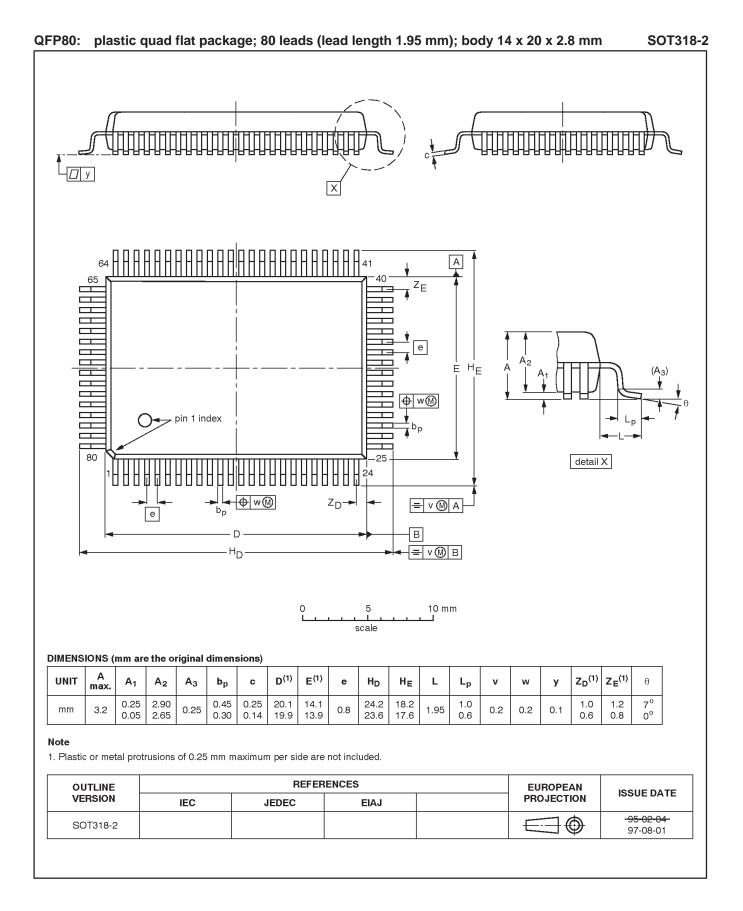
UNIT	А	A <sub>1</sub> min.	Α3	A <sub>4</sub> max.	bp	b <sub>1</sub>	D <sup>(1)</sup>	E <sup>(1)</sup>	e	е <sub>D</sub>	е <sub>Е</sub>	H <sub>D</sub>	HE	k	k <sub>1</sub> max.	Lp	v	w	У	Z <sub>D</sub> <sup>(1)</sup> max.	Z <sub>E</sub> <sup>(1)</sup> max.	β
mm	4.57 4.19	0.51	0.25	3.30	0.53 0.33			24.33 24.13			23.62 22.61				0.51	1.44 1.02	0.18	0.18	0.10	2.16	2.16	45 <sup>0</sup>
inches	0.180 0.165	0.020	0.01			0.032 0.026			0.05	0.930 0.890	0.930 0.890	0.995 0.985	0.995 0.985	0.048 0.042	0.020	0.057 0.040	0.007	0.007	0.004	0.085	0.085	

#### Note

1. Plastic or metal protrusions of 0.01 inches maximum per side are not included.

OUTLINE		REFEF	RENCES	EUROPEAN	ISSUE DATE	
VERSION	IEC	JEDEC	EIAJ	PROJECTION	13302 DATE	
SOT188-2	112E10	MO-047AC			<del>-92-11-17</del> 95-03-11	

SOT188-2



## 80C552/83C552

NOTES

## 80C552/83C552

#### Data sheet status

Data sheet status	Product status	Definition [1]
Objective specification	Development	This data sheet contains the design target or goal specifications for product development. Specification may change in any manner without notice.
Preliminary specification	Qualification	This data sheet contains preliminary data, and supplementary data will be published at a later date. Philips Semiconductors reserves the right to make chages at any time without notice in order to improve design and supply the best possible product.
Product specification	Production	This data sheet contains final specifications. Philips Semiconductors reserves the right to make changes at any time without notice in order to improve design and supply the best possible product.

[1] Please consult the most recently issued datasheet before initiating or completing a design.

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**Short-form specification** — The data in a short-form specification is extracted from a full data sheet with the same type number and title. For detailed information see the relevant data sheet or data handbook.

Limiting values definition — Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

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